

Problem 1.

$$A = \begin{pmatrix} 3 & 1 & 0 \\ 0 & 2 & 1 \\ -1 & -1 & 1 \end{pmatrix}$$

The secular equation is:  $\det |A - \lambda I| = (2 - \lambda)^3$

$\Rightarrow$  The eigenvalues are:  $\lambda_1 = \lambda_2 = \lambda_3 = 2$  (degenerate)

The eigenvalue equation yields:

$$x + y = 0; \quad z = 0; \quad x + y + z = 0$$

$\Rightarrow \vec{e} = x \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$  (only one eigenvector).

For convenience, we choose:  $\vec{e}_1 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$

$\Rightarrow \dim(\ker(A - \lambda I)) = 1$

$\ker(A - \lambda I)$  is the eigenspace for the eigenvalue  $\lambda$ .

The generalized  $\lambda$ -eigenspace is  $\ker[(A - \lambda I)^n]$  with the corresponding secular equation:  $\det |A - \lambda I| = (t - \lambda)^n g(t)$ .

$\Rightarrow \ker(A - \lambda I) \subset \ker[(A - \lambda I)^2] \subset \dots \subset \ker[(A - \lambda I)^n]$

For this case, we cannot have  $\dim(\ker[(A - \lambda I)^2]) = 3$ , so extend  $\vec{e}_1$  to a basis of  $\ker[(A - \lambda I)^2]$  given by  $\vec{e}_1, \vec{e}_2$  (i.e. find such  $\vec{e}_2$ ).

Let  $\vec{e}_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ . Now,  $\ker[(A - \lambda I)^2]$  must be  $\mathbb{R}^3$ .

so extend  $\vec{e}_1$  and  $\vec{e}_2$  to a basis of  $\mathbb{R}^3$  by, for example,

$$\vec{e}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

Now modify this basis by replacing  $\vec{e}_2$  by

$$\vec{e}_2' = (A - \lambda I)\vec{e}_3 = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

and by replacing  $\vec{e}_1$  with

$$\vec{e}_1' = (A - \lambda I)\vec{e}_2' = (A - \lambda I)^2 \vec{e}_3 = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}.$$

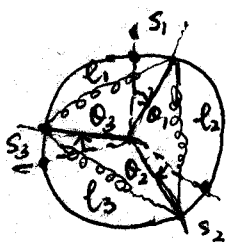
$\Rightarrow \vec{e}_1'$  still gives a basis of  $\ker(A - \lambda I)$  and  $\vec{e}_1', \vec{e}_2'$  together still give a basis of  $\ker[(A - \lambda I)^2]$ . So  $\vec{e}_1', \vec{e}_2'$  and  $\vec{e}_3$  give a basis of  $\mathbb{R}^3$ .

Form the matrix:  $P = (\vec{e}_1' \ \vec{e}_2' \ \vec{e}_3) = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}$

$$\Rightarrow P^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\Rightarrow P^{-1}AP = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ -2 & 1 & 1 \\ 0 & -2 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{pmatrix}$$

Problem 2.



$s_1, s_2, s_3$  are the coordinates of three beads along the circle.  $\theta_1, \theta_2$  and  $\theta_3$  are the corresponding angle coordinates.

$$\Rightarrow s_1 = a\theta_1, s_2 = a\theta_2, s_3 = a\theta_3.$$



$$\begin{aligned} \Delta l_1 = l_1 - l_0 &= 2a \left[ \sin\left(\frac{\pi}{3} + \frac{\theta_1 - \theta_3}{2}\right) - \sin\frac{\pi}{3} \right] \\ &\approx 2a \left[ \sin\frac{\pi}{3} + \cos\frac{\pi}{3} \cdot \frac{\theta_1 - \theta_3}{2} - \sin\frac{\pi}{3} \right] \\ &= -\frac{(\theta_3 - \theta_1)a}{2} = -\frac{s_3 - s_1}{2} \end{aligned}$$

$$\Delta l_2 = -\frac{(\theta_1 - \theta_2)a}{2} = -\frac{(s_1 - s_2)}{2}, \quad \Delta l_3 = -\frac{(\theta_2 - \theta_3)a}{2} = -\frac{(s_2 - s_3)}{2}$$

$\Rightarrow$  The kinetic energy of the system is:

$$T = \frac{m}{2} (\dot{s}_1^2 + \dot{s}_2^2 + \dot{s}_3^2) \frac{m}{m}$$

The potential energy is:

$$\begin{aligned} V &= \frac{k}{2} [(\Delta l_1)^2 + (\Delta l_2)^2 + (\Delta l_3)^2] = \frac{k}{8} [(s_3 - s_1)^2 + (s_1 - s_2)^2 + (s_2 - s_3)^2] \\ &= \frac{k}{2} \left[ \frac{s_1^2}{2} + \frac{s_2^2}{2} + \frac{s_3^2}{2} - \frac{s_1 s_2}{2} - \frac{s_2 s_3}{2} - \frac{s_3 s_1}{2} \right] \end{aligned}$$

Let  $m=1, k=1$ . We see:

$$[M] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1/m \end{pmatrix}, \quad [K] = \begin{pmatrix} \frac{1}{2} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{1}{2} \end{pmatrix}$$

with  $2T = [\dot{s}]^T [M] [\dot{s}]$ ,  $2V = [s]^T [K] [s]$

$\Rightarrow$  The secure equation is

$$|[K] - [M]\omega^2| = 0$$

With the normal modes:  $S_i = S_{i0} e^{i\omega t}$   $i=1,2,3$

$$\Rightarrow \begin{vmatrix} \frac{1}{2} - \omega^2 & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{2} - \omega^2 & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{1}{2} - \frac{M}{m} \omega^2 \end{vmatrix} = 0$$

$$\Rightarrow -\frac{3}{16} \frac{M}{m} \omega^2 - \frac{3}{8} \omega^2 + \left(\frac{1}{2} + \frac{M}{m}\right) \omega^4 - \frac{M}{m} \omega^6 = 0$$

$$\Rightarrow \omega_1^2 = 0, \quad \omega_2^2 = \frac{3}{4}, \quad \omega_3^2 = \frac{1}{4} \left(1 + \frac{2M}{\mu}\right) \quad (\text{Unit: } \frac{k}{m})$$

Substituting  $\omega_i$  ( $i=1,2,3$ ) into  $([K] - [M]\omega^2)[S] = 0$ :

$$\omega_1^2 = 0: \begin{pmatrix} \frac{1}{2} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{2} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} S_{11} \\ S_{21} \\ S_{31} \end{pmatrix} = 0 \Rightarrow S_{11} = S_{21} = S_{31} = S$$

$$[S]_1 = \begin{pmatrix} S \\ S \\ S \end{pmatrix}$$

$$\omega_2^2 = \frac{3}{4}: \begin{pmatrix} -\frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & \frac{1}{2} - \frac{3M}{4m} \end{pmatrix} \begin{pmatrix} S_{12} \\ S_{22} \\ S_{32} \end{pmatrix} = 0 \Rightarrow S_{32} = 0, \quad S_{12} = -S_{22} = \beta$$

$$[S]_2 = \begin{pmatrix} \beta \\ -\beta \\ 0 \end{pmatrix}$$

$$\omega_3^2 = \frac{1}{4} \left(1 + \frac{2M}{\mu}\right): \begin{pmatrix} \frac{1}{4} - \frac{M}{2\mu} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{1}{4} - \frac{M}{2\mu} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & -\frac{M}{4m} \end{pmatrix} \begin{pmatrix} S_{13} \\ S_{23} \\ S_{33} \end{pmatrix} \Rightarrow S_{13} = S_{23} = \alpha, \quad S_{33} = -\frac{2M}{\mu} \alpha$$

$$\Rightarrow [S] = \begin{bmatrix} S & \beta & \alpha \\ S & -\beta & \alpha \\ S & 0 & -\frac{2m}{\mu}\alpha \end{bmatrix}$$

Applying the normalized orthogonal condition:

$$[S]^T [M] [S] = I$$

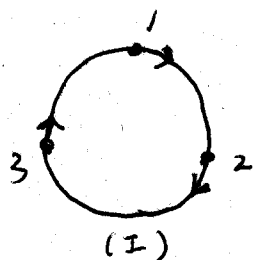
$$\Rightarrow \begin{cases} (2m + \mu)S^2 = 1 \\ 2m\beta^2 = 1 \\ (2m - \frac{4m^2}{\mu})\alpha^2 = 1 \end{cases}$$

$$\Rightarrow \begin{cases} S = \frac{1}{\sqrt{2m + \mu}} \\ \beta = \frac{1}{\sqrt{2m}} \\ \alpha = \frac{1}{\sqrt{2m + \frac{4m^2}{\mu}}} \end{cases}$$

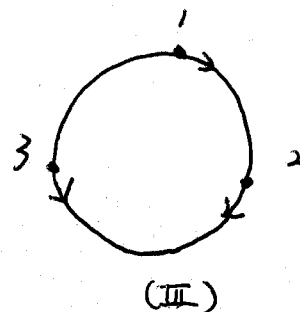
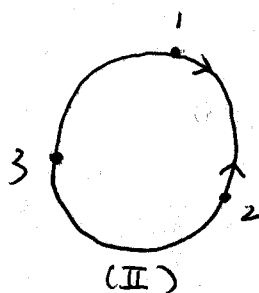
$$\Rightarrow \begin{pmatrix} S_1 \\ S_2 \\ S_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2m + \mu}} & \frac{1}{\sqrt{2m}} & \frac{1}{\sqrt{2m + \frac{4m^2}{\mu}}} \\ \frac{1}{\sqrt{2m + \mu}} & -\frac{1}{\sqrt{2m}} & \frac{1}{\sqrt{2m + \frac{4m^2}{\mu}}} \\ \frac{1}{\sqrt{2m + \mu}} & 0 & -\frac{2m}{\mu \sqrt{2m + \frac{4m^2}{\mu}}} \end{pmatrix} \begin{pmatrix} J_1 \\ J_2 \\ J_3 \end{pmatrix}$$

With  $J_1 = A + Bt$  ;  $J_2 = C_2 \sin\left(\frac{3k}{4m}t + \alpha_2\right)$  ;  $J_3 = C_3 \sin\left[\left(1 + \frac{2m}{\mu}\right)\frac{k}{4m}t + \alpha_3\right]$

The normal modes.



pure translation



(II) The two masses 1 and 2 are moving together. The mass 3 is stationary

(III) The two masses 3 and 2 are moving together. The mass 1 is moving along the same direction as mass 2.

## Problem 2

$$a) \quad y'''' + 4y'''' + 5y'' + 2y' = 0$$

$$(y'''' + 4y'''' + 5y'' + 2y') = C$$

$$\text{Because } y(0) = 1, \quad y'(0) = -1, \quad y''(0) = 2, \quad y'''(0) = -5$$

$$\Rightarrow C = 0$$

$$\text{i.e. } y'''' + 4y'''' + 5y'' + 2y' = 0$$

Define

$$y = y_1$$

$$y' = y_2$$

$$y'' = y_3$$

$$\text{then } \begin{pmatrix} y \\ y' \\ y'' \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$\begin{pmatrix} y' \\ y'' \\ y''' \end{pmatrix} = \begin{pmatrix} y_2 \\ y_3 \\ -2y_1 - 5y_2 - 4y_3 \end{pmatrix}$$

$$\therefore \begin{pmatrix} \dot{y}_1 \\ \dot{y}_2 \\ \dot{y}_3 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -5 & -4 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$\vec{A} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & -5 & -4 \end{pmatrix}$$

b)

$$\det |\vec{A} - \lambda \mathbb{I}| = \det \begin{pmatrix} -\lambda & 1 & 0 \\ 0 & -\lambda & 1 \\ -2 & -5 & -4-\lambda \end{pmatrix}$$

$$= \lambda^2(-4-\lambda) - 2 - 5\lambda = 0$$

$$\Rightarrow (\lambda+2)(\lambda+1)^2 = 0 \quad \text{i.e.} \quad \boxed{\lambda_1 = \lambda_2 = -1, \quad \lambda_3 = -2.}$$

when  $\lambda_1 = -1$ .

$$\vec{A} \cdot \vec{y} = -\vec{y} \Rightarrow \boxed{\vec{y} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}}$$

when  $\lambda_2 = -1$ .

$$\vec{A} \cdot \vec{y} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} + (-1)\vec{y} \Rightarrow \boxed{\vec{y} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}}$$

when  $\lambda_3 = -2$ .

$$\vec{A} \cdot \vec{y} = -2\vec{y} \Rightarrow \boxed{\vec{y} = \begin{pmatrix} 1 \\ -2 \\ 4 \end{pmatrix}}$$

c). Jordan normal form.

$$\Lambda = S^{-1}AS = \begin{pmatrix} -2 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix} \quad S = \begin{pmatrix} 1 & 1 & 1 \\ -2 & -1 & 0 \\ 4 & 1 & -1 \end{pmatrix}$$

$$d). \vec{u} = S^{-1} \vec{y}$$

$$\Rightarrow \dot{\vec{u}} = S^{-1} \dot{\vec{y}} = S^{-1} A \vec{y} = S^{-1} A S \vec{u} = \Lambda \vec{u}$$

$$\begin{pmatrix} \dot{u}_1 \\ \dot{u}_2 \\ \dot{u}_3 \end{pmatrix} = \begin{pmatrix} -2 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} -2u_1 \\ -u_2 + u_3 \\ -u_3 \end{pmatrix}$$

$$\therefore \dot{u}_1 = -2u_1 \quad \Rightarrow u_1 = a_1 e^{-2x}$$

$$u_2 = -u_2 + u_3$$

$$u_3 = -u_3 \quad \Rightarrow u_3 = a_3 e^{-x}$$

$$\therefore \dot{u}_2 = -u_2 + a_3 e^{-x} \quad \Rightarrow u_2 = (a_2 + a_3 x) e^{-x}$$

$$\Rightarrow \vec{u} = \begin{pmatrix} a_1 e^{-2x} \\ (a_2 + a_3 x) e^{-x} \\ a_3 e^{-x} \end{pmatrix}$$

$$e). \vec{y} = S \vec{u}$$

$$\vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ -2 & -1 & 0 \\ 4 & 1 & -1 \end{pmatrix} \begin{pmatrix} a_1 e^{-2x} \\ (a_2 + a_3 x) e^{-x} \\ a_3 e^{-x} \end{pmatrix}$$



$$\Rightarrow y_1 = (a_1 e^{-2x}) + (a_2 + a_3 x) e^{-x} + a_3 e^{-x}$$

$$y_2 = -2(a_1 e^{-2x}) - (a_2 + a_3 x) e^{-x}$$

$$y_3 = 4a_1 e^{-2x} + (a_2 + a_3 x) e^{-x} - a_3 e^{-x}$$

Insert initial condition.

$$y(0) = a_1 + a_2 + a_3 = +1$$

$$y'(0) = -2a_1 - a_2 = -1$$

$$y''(0) = 4a_1 + a_2 - a_3 = 2$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} \Rightarrow \begin{array}{l} a_1 = a_3 = 1 \\ a_2 = -1 \end{array}$$

$$\Rightarrow \boxed{y = e^{-2x} + x e^{-x}}$$