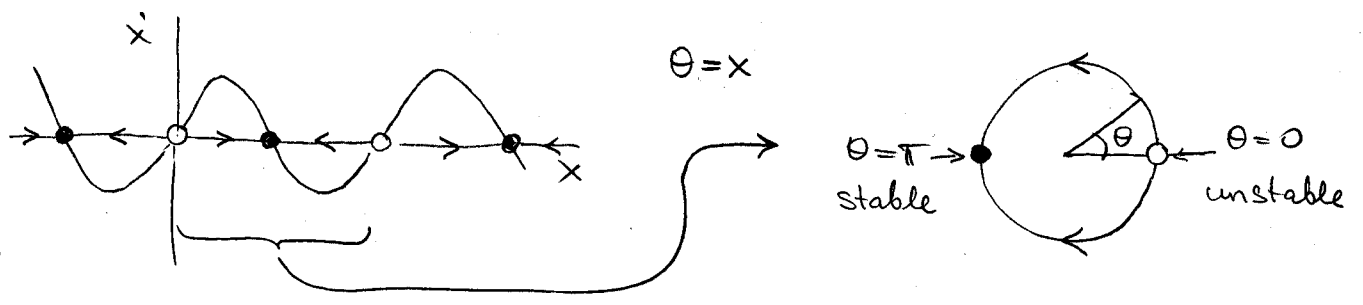


## Flows on the circle

$$\dot{x} = \sin x \leftarrow \text{periodic in } x$$



## Vector field on a circle:

Unique velocity for each point on the circle:

$$\dot{\theta} = f(\theta), \quad f(\theta + 2\pi) = f(\theta)$$

Remember: Oscillatory solutions possible!

## Uniform oscillator

$$\dot{\theta} = \omega$$

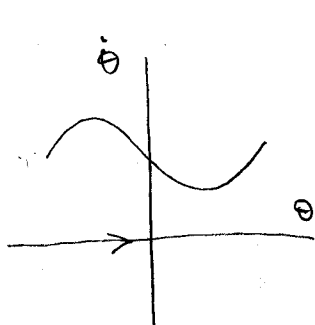
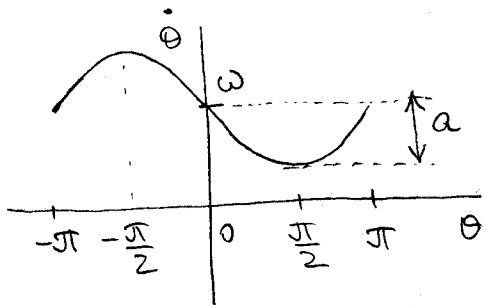
$$\theta(t) = \omega t + \theta_0 \quad - \text{periodic, } T = \frac{2\pi}{\omega}$$

- $\theta(t)$  - phase of the system
- no amplitude (1-d system)

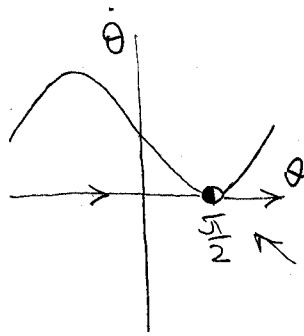
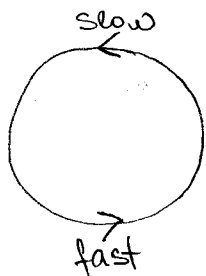
# Non-uniform oscillator

$$\dot{\theta} = \omega - a \sin \theta$$

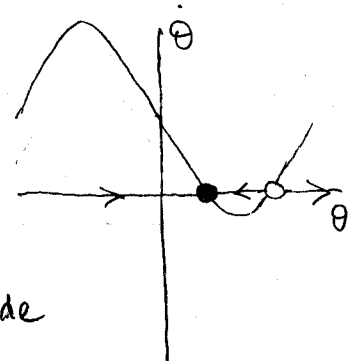
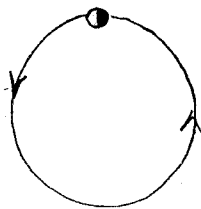
- phase locked loops (electronics)
- oscillating neurons
- fireflies
- Josephson junctions
- overdamped pendulum with torque



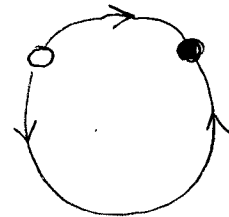
$a < \omega$



$a = \omega$



$a > \omega$



## Linear stability:

$$\sin \theta^* = \frac{\omega}{a}$$

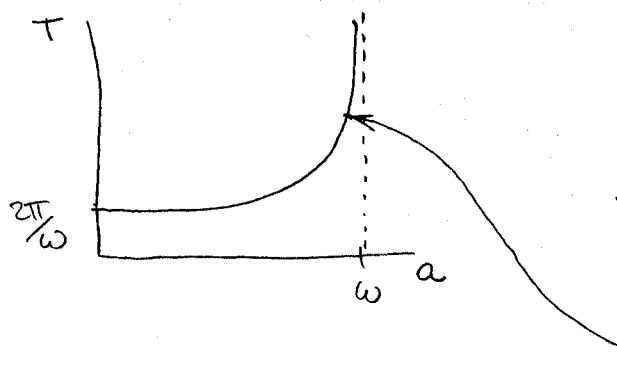
$$f'(\theta^*) = -a \cos \theta^* = \mp a \sqrt{1 - (\omega/a)^2}$$

$\cos \theta^* > 0$  - stable,  $\cos \theta^* < 0$  - unstable

Oscillation period

$$T = \int dt = \int \frac{dt}{d\theta} d\theta = \int_0^{2\pi} \frac{d\theta}{\omega - a \sin \theta} = \frac{2\pi}{\sqrt{\omega^2 - a^2}}$$

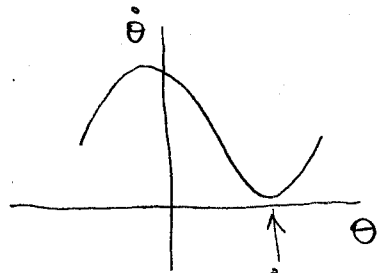
$$u = \tan \theta/2$$



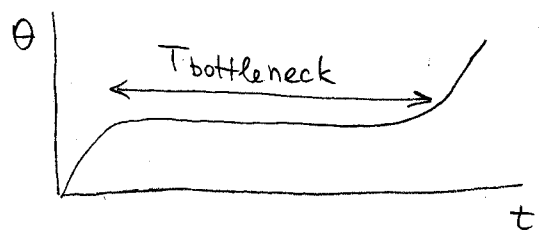
$$\sqrt{\omega^2 - a^2} = \sqrt{\omega+a} \sqrt{\omega-a} \approx \sqrt{2\omega} \sqrt{\omega-a}$$

$$\Rightarrow T \approx \pi \sqrt{\frac{2}{\omega}} \frac{1}{\sqrt{\omega-a}}, \quad a \rightarrow \omega$$

Ghosts & Bottlenecks:

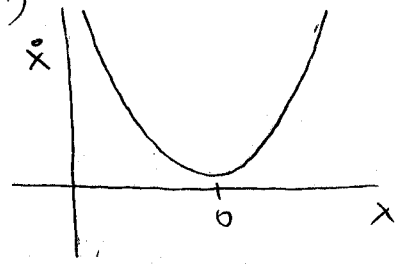


theta-dot - very small (ghost of a fixed point)



saddle-node -> locally parabolic

=> use normal form  $\dot{x} = r + x^2$



$$T_{\text{bottleneck}} \approx \int_{-\infty}^{+\infty} \frac{dx}{r+x^2} = \frac{\pi}{\sqrt{r}} \leftarrow \text{square root scaling}$$

In our example:  $f(\theta) = \omega - a \sin(\theta) = \omega - a \left(1 - \frac{1}{2}(\theta - \frac{\pi}{2})^2 + \dots\right)$   
 $\approx \omega - a + \frac{1}{2}a(\theta - \frac{\pi}{2})^2$

Rescale:  $x = (a/2)^{1/2} \phi$   
 $r = \omega - a$   
 $\Rightarrow (2/a)^{1/2} \dot{x} \approx r + x^2$

$$T \approx (2/a)^{1/2} \int_{-\infty}^{\infty} \frac{dx}{r+x^2} = (2/a)^{1/2} \frac{\pi}{\sqrt{\omega-a}} \approx \pi \sqrt{\frac{2}{\omega}} \frac{1}{\sqrt{\omega-a}}$$

Overdamped Pendulum:

$$mL^2\ddot{\theta} + b\dot{\theta} + mgL\sin\theta = \Gamma$$

↑  
strong damping  $\Rightarrow$  drop

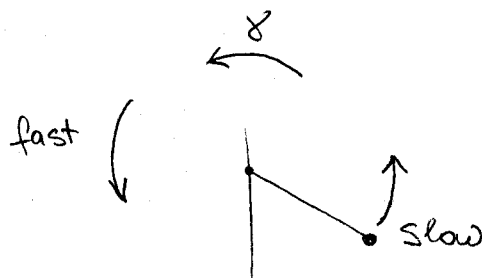
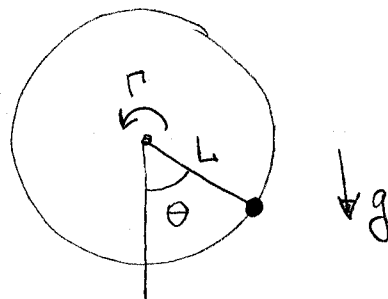
$$\left(\frac{b}{mgL}\right)\dot{\theta} = \left(\frac{\Gamma}{mgL}\right) - \sin\theta$$

$\Downarrow$   
 $T$

characteristic timescale

$\Downarrow$   
 $\gamma$

external torque!  
max. gravit. torque



$$\tau = t/T : \quad \frac{d\theta}{d\tau} = \theta' = \gamma - \sin\theta$$

Saddle-node bifurcation:  $\gamma = 1, \theta^* = \frac{\pi}{2}$  (torques balance)

Fireflies

Fireflies influence each other  $\Rightarrow$  synchronization

Periodic stimulus (flashing of other fireflies):

$$\dot{H} = \Omega, \quad H = 0 \Rightarrow \text{flash}$$

Firefly flashes:

$$\dot{\theta} = \omega + A \sin(H - \theta) \Leftrightarrow \begin{cases} \text{speed up, if behind stimulus} \\ \text{slow down, if ahead of stimulus} \end{cases}$$

↑  
resetting strength

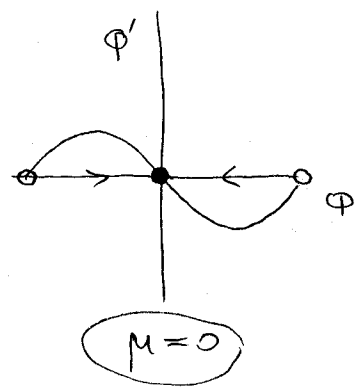
Phase difference,  $\phi = H - \theta$ :

$$\dot{\phi} = \dot{H} - \dot{\theta} = \Omega - \omega - A \sin\phi$$

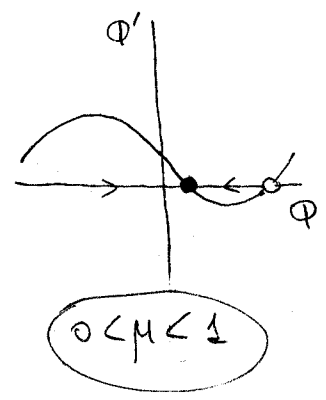
$$\tau = A t, \quad \mu = \frac{\Omega - \omega}{A}$$

(Ermentrout & Rinzel)

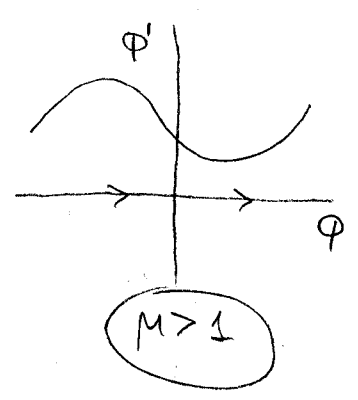
$$\phi' = \mu - \sin\phi$$



simultaneous flashes



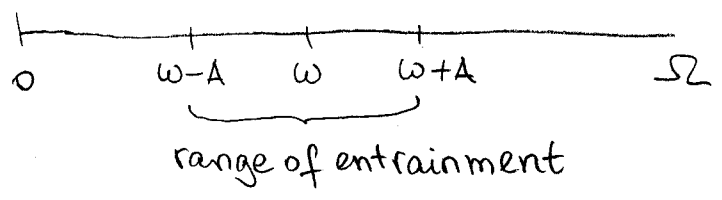
phase-locked  
(constant phase offset)



phase drift

Same period

different periods



Biological data:

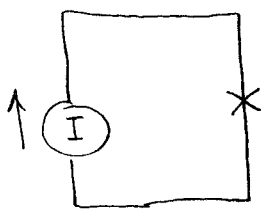
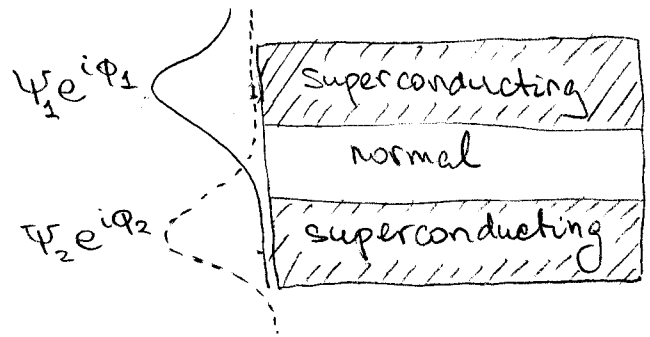
species with fixed  $\omega$  — good agreement

species with variable  $\omega$  — poor agreement (expected)

Superconducting Josephson junction

Ground state of SC:

Coherent "Cooper pairs" of electrons



Phase:  $\phi = \phi_1 - \phi_2$

Current  $I$

Voltage  $V$

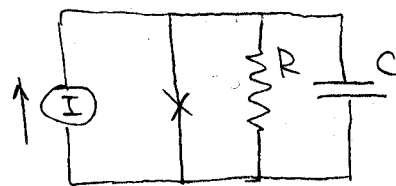
$I < I_c$ :  $\phi = 0, V = 0$

$I \geq I_c$ :  $I = I_c \sin \phi,$

$V = \frac{\hbar}{2e} \dot{\phi}$

Real Josephson junction:

total current = Josephson current  
+ ordinary current  
+ displacement curr.



$$C\dot{V} + \frac{V}{R} + I_c \sin \varphi = I \quad (\oplus) \quad V = \frac{\hbar}{2e} \dot{\varphi}$$

$$\Rightarrow \frac{\hbar C}{2e} \ddot{\varphi} + \frac{\hbar}{2eR} \dot{\varphi} + I_c \sin \varphi = I \leftarrow \text{same equation as for damped pendulum}$$

Dimensionless form:

timescale:  $t_0 = \frac{\hbar}{2eI_c R} \Rightarrow \tau = t/t_0$

McCumber parameter:  $\beta = \frac{2eI_c R^2 C}{\hbar}$  (dimensionless capacitance)

$$\beta \varphi'' + \varphi' + \sin \varphi = \frac{I}{I_c}$$

For small  $\beta$  (typically  $10^{-6} \lesssim \beta \lesssim 10^6$ )

$$\varphi' = \frac{I}{I_c} - \sin \varphi$$

I-V curve:

$$\langle V \rangle = \frac{\hbar}{2e} \langle \dot{\varphi} \rangle = \frac{\hbar}{2e} \frac{1}{t_0} \langle \varphi' \rangle = I_c R \langle \varphi' \rangle$$

$$\langle \varphi' \rangle = \frac{1}{T} \int_0^T \frac{d\varphi}{d\tau} d\tau = \frac{1}{T} \int_0^{2\pi} d\varphi = \frac{2\pi}{T} = \sqrt{\left(\frac{I}{I_c}\right)^2 - 1}$$

← already calculated

$$\langle V \rangle = I_c R \sqrt{\left(\frac{I}{I_c}\right)^2 - 1}, \quad I > I_c$$

$$= 0, \quad I < I_c$$

